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AMENDMENTS

Please amend the claims as follows:

- 1. (previously presented) A method for adaptive ultrasound imaging, the method comprising:
- (a) obtaining data from a plurality of transducer elements across a receive aperture;
- (b) determining a coherence factor as a function of the data across the receive aperture; and
 - (c) setting a beamforming parameter as a function of the coherence factor.
- 2. (original) The method of Claim 1 wherein (b) comprises calculating a ratio of coherent sum to an incoherent sum.
- 3. (original) The method of Claim 1 wherein (b) comprises calculating phase variance across transducer elements.
- 4. (original) The method of Claim 1 wherein (b) comprises calculating the coherence factor as a function of data altered by beamforming delays prior to summation.
- 5. (original) The method of Claim 1 wherein (c) comprises setting a transmit beamforming parameter; and

further comprising:

- (d) transmitting acoustic energy as a function of the transmit beamforming parameter.
- 6. (original) The method of Claim 1 wherein (c) comprises setting a receive beamforming parameter; and

further comprising:

- (d) receiving acoustic energy as a function of the receiver beamforming parameter.
- 7. (original) The method of Claim 1 wherein (c) comprises setting an aperture size as a function of the coherence factor.
- 8. (original) The method of Claim 7 wherein (c) comprises setting a sub-aperture size.
- 9. (original) The method of Claim 1 wherein (c) comprises setting an apodization profile as a function of the coherence factor.
- 10. (original) The method of Claim 1 wherein (c) comprises setting one of a delay and phase profile as a function of the coherence factor.
- 11. (original) The method of Claim 1 further comprising:
 - (d) setting an image forming parameter as a function of the coherence factor.
- 12. (original) The method of Claim 1 wherein (c) comprises setting a complex aperture parameter as at least two of: apodization profile, aperture size, delay profile, and phase profile.
- 13. (previously presented) A system for adaptive ultrasound imaging, the system comprising:
 - a transducer having a plurality of elements in an array;
- a processor operable to determine a coherence factor across the array as a function of data from the elements; and
- a beamformer connected with the transducer, a beamforming parameter of the beamformer responsive to the coherence factor.

- 14. (original) The system of Claim 13 wherein the beamformer comprises one of a transmit beamformer, a receive beamformer and combinations thereof.
- (original) The system of Claim 13 wherein the beamforming parameter comprises one 15. of: an aperture, an apodization profile, a delay profile, a phase profile and combinations thereof.
- 16. (currently amended) A method for adaptive ultrasound imaging, the method comprising:
 - (a) obtaining data from a plurality of transducer elements;
 - (b) determining a coherence factor as a function of the data; and
- (c) setting an image forming parameter as a function of the coherence factor, the image forming parameter being for synthesis, eompounding, multibeam, a number of sequential beams, a number of sub-apertures, a number of focal zones, or combinations thereof.
- 17. (currently amended) The method of Claim 16 wherein (c) comprises setting a parameter for one of synthesis and compounding.
- 18. (original) The method of Claim 16 wherein (b) comprises calculating a ratio of coherent sum to an incoherent sum.
- 19. (original) The method of Claim 16 wherein (b) comprises calculating phase variance across transducer elements.
- 20. (original) The method of Claim 16 wherein (b) comprises calculating the coherence factor as a function of the data altered by beamforming delays prior to summation.

- 21. (original) The method of Claim 16 wherein (c) comprises setting a number of simultaneous beams.
- 22. (original) The method of Claim 16 wherein (c) comprises setting a number of sequential beams.
- 23. (original) The method of Claim 16 wherein (c) comprises setting one of: a number of sub-apertures, a number of focal zones in a same scan line and combinations thereof.
- 24. (original) The method of Claim 16 wherein (c) comprises setting a number of beams compounded together.
- 25. (original) The method of Claim 16 wherein (c) comprises setting one of: transmit multibeam parameters, receive multibeam parameters and combinations thereof.
- 26. (original) The method of Claim 16 wherein (c) comprises setting a number of receive sub-apertures;

further comprising:

- (d) coherently summing ultrasound data within each of the sub-apertures; and
- (e) incoherently summing coherent sum outputs of at least two sub-apertures of (d).
- 27. (previously presented) A system for adaptive ultrasound imaging, the system comprising:
 - a transducer having a plurality of elements;
- a coherence factor processor operable to determine a coherence factor as a function of ultrasound data from the elements; and
- an image forming processor operable to form images as a function of the coherence factor;

wherein the image forming processor is operable to set one of: a number of simultaneous beams, a number of sequential beams, a number of sub-apertures, a number of focal zones in a same scan line, a number of beams compounded together, transmit multibeam parameters, receive multibeam parameters and combinations thereof.

- 28. (original) The system of Claim 27 wherein the image forming processor comprises a compound processor.
- 29. (cancelled)
- 30. (previously presented) A method for adaptive ultrasound imaging, the method comprising:
 - (a) obtaining ultrasound data from a plurality of transducer elements;
 - (b) determining a coherence factor as a function of the ultrasound data; and
- (c) setting a dynamic range, a nonlinear filter, a nonlinear map, or combinations thereof as a function of the coherence factor.
- 31. (original) The method of Claim 30 wherein (c) comprises setting the dynamic range as a function of the coherence factor.
- 32. (original) The method of Claim 30 wherein (c) comprises setting the nonlinear filter as a function of the coherence factor.
- 33. (original) The method of Claim 30 wherein (c) comprises setting the nonlinear map as a function of the coherence factor.
- 34. (previously presented) A system for adaptive ultrasound imaging, the system comprising:
 - a transducer having a plurality of elements;

a coherence factor processor operable to determine a coherence factor as a function of ultrasound data from the elements; and

an image processor operable to set a dynamic range, a nonlinear filter, a nonlinear map, combinations thereof as a function of the coherence factor.